$-1$   $62-5016$ 

**62-5016**

**Instruction Manual**

**for**

# **Model 2590 (Average Sensing) Model2590R (True RMS)**

# *5 V2* **-Digit DIGITAL MULTIMETER**

! **DELTA ELECTRONICS LABORATORY** NBS Traceable Calibration 2402 S. Nashville Ave.





62-5016, **Rev 1**



Printed in the U.S.A. Copyright, 1982

Instruction Manual

for

# **Model 2590** (Average Sensing) Model 2590R (True RMS),

# 51/2 -Digit DIGITAL MULTIMETER



## **CONTENTS**

#### 1. **INTRODUCTION**

- 1.1 Generai
- 1.2 Ordering Information

#### 2. **SPECIFICATIONS**

- 2.1 DC Volts
- 2.2 AC Volts
- 2.3 DC Current
- 2.4 AC Current
- 2.5 Resistance
- 2.6 Generai Performance
- 2.7 Accessories

#### 3. **OPERATION**

- 3.1 Generai
- 3.2 Unpacking & Repacking
- 3.3 Safety Markings
- 3.4 Power Connection
- 3.5 Operating Controls & Indicators
- 3.6 Input Connections
	- 3.6.1 Voltage & Current Measurements
	- 3.6.2 Resistance Measurements (2W/4W)
	- 3.6.3 Diode Characteristic

#### 4. **CALIBRATION**

- 4.1 Generai
- 4.2 Standards & Measuring Instruments
- 4.3 Access to Calibrating Adjustments
- 4.4 Procedures
	- 4.4.1 DCV Calibration
	- 4.4.2 KQ Calibration
	- 4.4.3 Model 2590 ACV Calibration
	- 4.4.4 Model 2590R ACV Calibration

#### ©ANALOGIC CORPORATION, DATA PRECISION DIVISION **iii**

#### **PROPRIETARY NOTICE**

The information contained in this publication is derived in part from proprietary and patent data of the Data Precision Corporation, a Division of Analogie Corporation. This infomation has been prepared for the express purpose of assisting operating and maintenance personnel in the efficient use of the instrument described herein. Publication of this information does not convey any rights to use or reproduce it or to use it for any purpose other than in connection with the installation, operation, and maintenance of the equipment described herein.

> First Edition - Aprii, 1982 Second Edition - October, 1982 Copyright 1982. Ali rights reserved. Printed in U.S.A.

#### **5\_ PRINCIPLES OF OPERATION**

- 5.1 Instrument Block Oiagram
	- 5.1.1 Generai
	- 5.1.2 Measurement Modes & Input Signal Condition-
	- ing
	- 5.1.3 Analog-to-Oigital Conversion
	- 5.1.4 System Timing
- 5.2 Input Terminals *I* Mode Switching
- 5.3 Signal Conditioning

5.3.1 Generai

- 5.3.2 OCV Signal Conditioning
- 5.3.3 ACV Signal Conditioning
- 5.3.4 Current Measurements Signal Conditioning
- 5.3.5 Resistance Measurements Signal Conditioning

5.4 AID Conversion

5.4.1 Analog Section 5.4.2 AlO Reference Generation (Isopolar) 5.4.3 Timing Control Logic

5.5 Oisplay

5.6 Power Supplies

#### **6. MAINTENANCE**

6.1 Generai

- 6.2 Trouble Shooting Strategy
- 6.3 Power Supply
- 6.4 AID Conversion

#### **7. PARTS LlSTS**

7.1 Generai; Model 2590 Assemblies

7.2 Parts Lists

- 7.2.1 Generai
- 7.2.2 Ordering Information
- 7.3 Main PCB Assembly (67-1117)
- 7.4 Logic PCB Assembly (67·1115)
- 7.5 Oisplay PCB Assembly (67·1116)
- 7.6 Front Bezel Assembly (67·1119)
- 7.7 Rear Panel Assembly (67·1120)
- 7.8 Average ACIDC Assembly (67·1113)
- 7.9 True RMS ACIDC Assembly (67·1114)

#### **MODEL 2590 SERIES DMM 62-5016**

#### 8. **REFERENCE DRAWINGS**

Assembly Orawings: Main PCB (A1): 67·1117 Oisplay PCB (A2): 67·1116 Logic PCB (A3): 67·1115 Switch Module (A4): 67·1130 Front Bezel: 67·1119 Rear Panel: 67·1120 ACG ACIDC PCB (A5): 67·1113 RMS ACIDC PCB (A5): 67·1114

#### Schematics:

Main PCB (A1): 65·1040 Sheet 1) Logic (A3) and Oisplay (A2): 65·1040 (Sheet 2) Switch Module (A4): 65·1039 AVG ACIDC (A5): 65·1038 RMS ACIDC (A5): 65-1037

**iv**  $\odot$  ANALOGIC CORPORATION, DATA PRECISION DIVISIC

**T**



**Frontispiece. Model 2590/2590R DMM**

#### **MODEL 2590 SERIES DMM 62-5016**

# **Chapter 1 INTRODUCTION**

#### **1.1 GENERAL**

Data Precision Model 2590/2590R Digital Multimeter (DMM) is a 5% digit, generai purpose, rugged and reliable bench-top performer. Its light weight assembly, mounted in a high impact-proof plastic case with integral carrying handle tilt stand makes it an ideai precision meter for laboratory and servicing applications.

The Model 2590/2590R provides 25 Measuring Function/Range Capabilities, including DCV, ACV, DCmA, ACmA, and 2- or 4-Wire KQ measurements, with resolutions of 1 microvolt, 1 nanoampere, and 1 milliohm for voltage, current, and resistance measurements, respectively. In addition, the constant-current sourcing technique used for the resistance measurement function, in conjunction with the decade scaling introduced by the range switching, may be used for convenient measurement of diode characteristics.

Input circuitry is protected against application of peak voltages up to 1200 V on ali voltage ranges, up to 500 Vdc or ac rms on ali resistance measurement ranges, and currents up to 2 amperes. The DMM is protected against damage for currents over 2 amperes by a field-replaceable internai fuse rated for 2A @ 250 V. Open circuit voltages do not exceed 3.5 volts when measuring resistances.

High common mode rejection of 160 dB at dc and over 120 dB at 50 and 60Hz, and over 80 dB normal mode rejection ratio beginning at 50 Hz and at ali 10-Hz increments thereafter, enhance the applications in harsh industriai environments.

**vi** ©ANALOGIC CORPORATION, DATA PRECISION DIVISION

#### 62·5016 MODEL 2590 SERIES DMM 62·5016

#### MODEL 2590 SERIES DMM

The display of 0.56" (14.22 mm) LED display digits provide excellent visibility even in high level ambient light. They are mounted immediately behind a front panel optical filter for wide-angle, parallax-free readings. Polarity is displayed automatically for dc measurements, and the decimai point is positioned automatically in ali measurements so that readings are made directly in units indicated by the range scale selection. The display digits are blanked for out-of-range signals, leaving the decimal point and polarity sign (if dc measurement) lighted to indicate an operable multimeter and to avoid making invalid readings of out-of-range signals.

### 1.2 ORDERING CONFIGURATIONS

Model 2590 DMM and Model 2590R provide ali of the features above. The Model 2590 senses the average value of the accoupled input and calibrates the display for an equivalent sinewave. The Model 2590R performs a true rms sensing of the ac-coupled input. In this instruction manual, unless stated otherwise, references to the Model 2590 are applicable to both instruments.

Both models of the multimeter are available for different powering mains installations. The standard model (no suffix) is intended for use with 105 to 125 V, 50 to 400 Hz sources; the "E" suffix denotes instruments intended for use with 210 to 250 V, 50 to 400 Hz sources; and the "J" suffix denotes instruments intended for use with 91 to 109 V, 50 to 400 Hz sources. Power consumption is less than 10 watts from all sources. A rear-panel-mounted fuse, in series with the sourcing power, provides overload protection.

A number of accessories are available for use with the multimeter. Refer to paragraph 2.7 for details.

## **Chapter 2 SPECIFICATIONS**

#### 2.1 DC VOLTS



\*Maximum Input Voltage: ± 1200 Vdc or peak ac on ali ranges.

#### Accuracy:

#### 200mV Range:



24 Hours (@ 23°C  $\pm$  1°C):  $\pm$  (0.004% inp. + 2 digits 1 Year (@ 23°C ± 5°C):  $\pm$  (0.007% inp. + 2 digits

#### 2000V Range:



Temperature Coefficient ( $0^{\circ}$ C to + 45 $^{\circ}$ C):



#### Common Mode Rejection Ratios (minimum):

At dc: 160 dB with 1000 $\Omega$  source impedance unbalance At 50/60 Hz: 120 dB with 1000Q source impedance unbalance

#### Normal Mode Rejection Ratio:

50 Hz and at ali 10Hzincrements above: >80 dB

#### MODEL 2590 SERIES DMM 62-5016

## 2.2 AC VOLTS



#### \*Maximum Input Voltage:



#### Input Impedance, ali ranges:

 $1 M\Omega$  | <100 pF

#### Model 2590R (True RMS Sensing, AC Coupled)

Accuracy\* (1 year @ 23°C  $\pm$  5°C) For Crest Factor  $\leq$  3':

#### 2V, 20V, 200V, and 2000V Ranges:



#### 200mV Range:



\*Interpolate linearly between indicated frequencies.

#### Temperature Coefficient ( $0^{\circ}$ C to + 45 $^{\circ}$ C):

#### 2V, 20V, 200V, and 2000V Ranges:



#### 200mV Range:





## MODEL 2590 (Average Sensing, Calibrated in RMS of Sinewave)

Accuracy\* (1 year  $@ 23°C \pm 5°C$ )

2V, 20V, 200V, and 2000V Ranges:



#### 200mV Range:



\*Interpolate linearly between frequencies.

#### Temperature Coefficient ( $0^{\circ}$ C to + 45°C):





#### Voltage Coefficient:

Add  $\pm$  1/<sub>2</sub> ppm/volt.

*q*

2.3 DC CURRENT



Accuracy (1 year  $@ 23°C \pm 5°C$ ):

 $200\mu$ A,  $2mA$ , and  $20mA$  Ranges:

 $\pm$  (0.1% inp. + 10 digits)

200mA and 2000mA Ranges:  $\pm$  (0.2% inp. + 10 digits)

Temperature Coefficient ( $0^{\circ}$ C to + 45 $^{\circ}$ C):

2mA, and 20mA Ranges:  $\pm$  (0.01% inp. +1 digit)/°C  $^{1\text{np.}+20\text{dists}}$ 200uA +\-(0.1%)

200mA and 2000mA Ranges:

 $\pm$  (0.02% inp. + 1 digit)/°C

#### 2.4 AC CURRENT



#### MODEL 2590R (True RMS Sensing)

#### Accuracy\*(1 year  $@ 23°C \pm 5°C$ )



#### MODEL 2590 SERIES DMM 62-5016

#### Temperature Coefficient ( $0^{\circ}$ C to + 45 $^{\circ}$ C):

20 Hz to 1 KHz:  $\pm (0.03\% \text{ inp.} + 20 \text{ digits}).$ <sup>o</sup> 5 KHz to 20 KHz:  $\pm (0.1\% \text{ inp.} + 30 \text{ digits})/0$ 

\*Linearly interpolate between stated points. Valid for readings  $\geq 10\%$  of full scale.

#### MODEL 2590 (Average Sensing, Calibrated in RMS of Sinewave)

Accuracy\* (1 year  $@$  23°C  $\pm 5$ °C)



#### Temperature Coefficient\* ( $0^{\circ}$ C to + 45 $^{\circ}$ C):

20 Hz to 1 KHz:  $\pm (0.02\% \text{ inp.} + 4 \text{ digits})/00$ 5 KHz to 20 KHz:  $\pm (0.05\% \text{ inp.} + 4 \text{ digits})/00$ 

\*Linearly interpolate between stated points.

#### 2.5 RESISTANCE



#### \*\*Absolute Accuracy: ± 10%;

Ratio Accuracy: Same as kQ Accuracy. For example:  $(1 \text{mA}/100 \mu\text{A}) \pm 0.007\%$ .  $(1mA/1<sub>\mu</sub>A) \pm 0.03\%$ .

Maximum Open Circuit Voltage:  $<$  3.5 volts

Accuracy (1Year,  $23^{\circ}$ C  $\pm$  5°C)

Range

Temperature Coefficient ( $0^{\circ}$ C to + 45 $^{\circ}$ C):

Configuration:

MODEL 2590 SERIES DMM 62-5016

Stand:

Adjustable, removable tilt-stand, for optimum viewing while on bench.

#### Case:

Polystyrene (bench/portable) Dimensions (overall, including tilt stand): 8% "W (21.6cm) x 27/s"H (7.3cm) x 87/a"D (22.5cm) Environmental: Operating Temperature: 0° to 45°C

Storage Temperature:  $-25^{\circ}$ C to 60 $^{\circ}$ C Relative Humidity: 95% max, except 80% max above 40°

#### Power:

10W, max. 50 to 400 Hz

Model 2590/2590R: 105 to 125 V Model 2590E/2590RE: 210 to 250 V Model 2590J/2590RJ: 91 to 109 V

#### 2.7 ACCESSORIES

The following accessories are available to extend the Model 2590/2590R DMM performance. They may be obtained from the Data Precision Distributors.



\*Included as standard item at no additional charge.

 $20 \text{M}\Omega$   $\pm (0.02\% \text{ inp.} + 5 \text{ digits})/00$ Settling Time (seconds) to Final Value  $\pm$  0.01%:

Range(s)

 $0.1 + (0.3 \times$  resistance in megohms)

True 4-wire, or 2-wire, switch selected

 $200\Omega$   $\pm (0.01\%$  inp.  $+ 4$  digits

 $200\Omega$   $\pm (0.001\% \text{ inp.} + 0.5 \text{ digits})/00$ 

 $2000k\Omega$   $\pm (0.005\%$  inp.  $+1$  digit)/°C

Accuracy

Coefficient

 $2000k\Omega$   $\pm (0.03\%$  inp.  $+3$  digits  $20M\Omega$   $\pm$  (0.25% inp. + 11 digits

 $2k\Omega/20k\Omega/200k\Omega$   $\pm$  (0.007% inp. + 2 digits

 $2k\Omega/20k\Omega/200k\Omega$   $\pm (0.001\% + 0.2 \text{ digit})/^{\circ}C$ 

#### Overvoltage Protection

 $± 500$  Vdc or rms ac.

#### 2.6 GENERAL PERFORMANCE

#### Common Mode Voltage:

500 Vdc or peak ac, input LO to earth.

#### Display:

LED display, 0.56" high, 7-segment, full  $+$  (plus) and  $-$  (minus).

#### Conversion Rate:

2.5 Conversions per second

#### Weight:

3.01b (1.4Kg) net

## ©ANALOGIC CORPORATION, DATA PRECISION DIVISION

©ANALOGIC CORPORATION, DATA PRECISION DIVISION 2-7

## **Chapter 3 OPERATION**

**NOTE:** Read this chapter carefully before using your Model 2590/2590R DMM. Observe ali WARNINGS and CAUTIONS.

#### **3.1 GENERAL**

Chapter 3 contains detailed instructions for connecting and operating the Model 2590, including safety precautions to prevent harm to personnel or damage to equipment. Refer to the specifications in Chapter 2 to obtain the tolerance with which displayed measurements may be interpreted. Instructions for recalibrating the instrument are contained in Chapter 4.

#### **3.2 UNPACKING & REPACKING**

Figure 3-1 identifies the components of the packaging configuration for Model 2590/2590R DMM. As shown in that illustration, the multimeter and an activated dessicant are placed in a waterproof plastic wrapper and securely fitted between molded-foam shock isolators. The probe is placed inside its own waterproof plastic bag, while spare fuses and alligator clip are placed in a separate waterproof bag. The two smaller bags and the documentation are placed in the space formed between the foam isolators, and ali fitted within the sturdy shipping carton. When unpacked, you should find:

(1) Model 259/2590R DMM

(2) Test Probe Assembly & Alligator Clips

- (3) Certificate of Conformance
- (4) Warranty Card
- (5) Factory Test Data Sheet

(6) Spare 2A, 250V, 3AG Fuse, FastBlo (for current in-

- put)
	- (7) Spare %A (2590) / 1/8A (2590R), 250V, 3AG Fuse SloBlo (for power line input) *(8)* Instruction Manual, P/N 62-5016

Carefully examine these articles, noting especially the matching serial numbers of the instrument and the test data. Inspect the packing case and the instrument for any signs of damage during shipment and report immediately to the carrier. Fili out and return the warranty card to register your instrument and to establish your warranty service interval.

Accessories, such as spare leads or high voltage probes, may have been ordered. These will be shipped in their own containers.

Retain the packing material for reshipment. When shipping Model 2590 DMM, piace the instrument in a waterproof protective bag; use molded-foam isolators; include the probe set; and pack in originai shipping carton, if available. If the foam shock isolators are not available, use a suitable shock isolating material, such as bubble plastic, to obtain a firm package.



Fig. 3-1. Model 2590/2590R, Shipping Configuration

## MODEL 2590 SERIES DMM 62-5016

## 3.3 SAFETY MARKINGS

The front panel incorporates several standared operator warnings (See, also, Figure 3-2 and Figure 3-3.):



Located in the center of the four input terminals. This cautions the operator about limitations to the signals that may be connected to the terminals and advises him to refer to the instruction manual before connecting to them.

*f*

This warns the operator that there may be dangerously high voltage at this location, or that there is a voltage limitation to be considered when using these terminals.

Located above and to the right of the terminals.

1200 V 800 VAC

Located between the HI and LO panel markings to the right of the input terminals. These specify the limiting voltages (1200 Vdc or 800 Vac) that may be applied between these terminals.

 $+500$  V MAX Located beneath the input terminai group and above the symbol for earth (or case) ground, with a leader line to the LO terminai pair. This specifies the maximum common mode voltage  $(± 500$  Vdc or peak ac) that may be tolerated between input LO and earth ground.

2A MAX Located beneath the mA selector switches. This specifies the maximum current (2A) that may be connected to the input terminals when making current measurements.

The rear panel mounts a standard grounding lug, electrically connected to the "ground" terminai of the 3-wire line cord receptacle in the rear panel. It is identified with an adjacent panel marking of the standard earth ground reference symbol.

©ANALOGIC CORPORATION, DATA PRECISION DIVISION 3·3

#### 3.4 POWER CONNECTION

A different configuration of the Model 2590 series DMM is available for powering from any of the nominai power sources universally available: Model 2590 or 2590R for 105 to 125 Vac, Model 2590E or 2590RE for 210 to 250 Vac, and Model 2590J or 2590RJ for 91 to 109 Vac; with line frequencies from 50 to 400 Hz. Before plugging the attached 3-wire power cord into the power source, check the model designation and power source specification on the label located on the rear panel, See Figure 3-3.

If correct power is available, plug in the power cord.

Turn on power at front panel and allow at least  $\frac{1}{2}$  hour warmup in order to achieve in-spec performance.

#### 3.5 OPERATING CONTROLS & INDICATORS

Figure 3-2 identifies the front-panel performance features and Table 3-1 includes a description of the function of each,

Figure 3-3 identifies the rear panel features, while Table 3-2 includes a description of these items.



#### MODEL 2590 SERIES DMM 62-5016

#### Table 3·1 Model 2590 DMM Front-Panel Controls & Indicators



• Reference Symbol Designations as used in the schematic for the controls are shown in parentheses.

©ANALOGIC CORPORATION, DATA PRECISION DIVISION

#### Table 3·2 MODEl *2590/2590R* REAR PANEl FEATURES





### 3.5 SIGNAl CONNECTIONS

#### CAUTION

Observe applicable maximum voltage ratings for ali connections. (Refer to Chapter 2, Specifications.) Failure to comply with voltage ratings may result in equipment damage or hazardous operating conditions.

### 3.5.1 Voltage Measurement Connections

a. Connect unknown voltage high and low to the Model 2590 terminals as shown in Figure 3-4.

b. Operate DCV or ACV front-panel Mode switch.

c. Operate an appropriate range switch for the anticipated unknown voltage value to provide the maximum resolution in the display (or consistent with the accuracy of the required information).

d. Read the display. The dc voltage values will be displayed with the polarity sign. The ac voltage values will be displayed without sign, and the value will be displayed in volts rms. The calculation is determined according to the particular model and corresponding ac-to-dc converter that is installed. That is, average-sensed, true rms including the dc component, or rms excluding the dc component. The decimai point will be positioned automatically so that the value will be direct reading in volts. If the input exceeds the maximum reading of the selected range (refer to the Specifications), the message Ol will appear.



3·7

## **Chapter 4 RECALIBRATION**

4.1 GENERAL

#### CAUTION

Recalibration requires access to the interior of the instrument, allowing exposure to high voltages. Only qualified personnel should perform the operations described in this chapter.

Model 2590/2590R digital multimeters have been manufactured with precision, stable parts, and have been thoroughly tested, calibrated, and burned in prior to shipment. They are ready for use immediately upon receipt and are designed for extensive operating cycles with specified performance. The results of the comprehensive testing and factory calibration are recorded on the test data sheets shipped with every instrument, and these should be retained for reference when recalibration may be required.

Specified performance should be checked regularly at s-month intervals, if possible, to determine the need for recalibration. Follow the procedures in the sequence described in this chapter when such recalibration may be required.

#### WARNING

Removal of the 2590 top cover for recalibration adjustments will expose high voltages (power line potentials). Use caution when making adjustments.

3.6.2 Resistance Measurements

When making resistance measurements of very high impedance sources, as when required to measure resistance on the 20MQ-range, the input circuit may be susceptible to noise. The effect of voltage-producing noise fields on the probe leads may be sufficient to introduce significant changes in the least significant digits of the 5%·digit display.

Measurement errors may be kept to a minimum under these circumstances by using the 4·wire measurement confiquration, and by keeping the leads as short as possible. Do not use any extensions on the probes. In addition, twist the probe leads so as to equalize any field effects on the signal input leads.

#### 3.6.3 Measuring Diode Characteristics

The Model 2590 provides a convenient instrument for the measurement of diode characteristics as a subset of the resistance-measuring operations.

(1) Connect the diode to the input terminals, as shown.

(2) Select the Resistance Measurement mode.

(3) Select the  $20M\Omega$  resistance range scale. The current applied at this range is 100nA (approx).

(4) Record the display value. It represents the resistance of the diode in megohms, and is converted to the voltage across the diode by multiplying by the current value of 100nA. The mathematics is simplified by requiring only a decimal point move.

(5) Repeat steps (3) and (4) for the other current excitations. The applied current is increased in decade steps as the range selection is changed to the lower ranges, while the resistance is indicated in kilohms.

(6) Plot the Voltage-Current characteristic curve for the recorded and calculated values.

Note: By keeping the excitation to less than 0.25V, the Model 2590 makes it possible to perform in-circuit measurements safely.

#### **4.2 TEST STANDARDS & MEASURING INSTRUMENTS**

#### DC Voltage Source:

Adjustable output to 1000 volts;  $\pm$  0.002% accuracy. Data Precision Model 8200, or equivalent

62-5016

AC Voltage Source:

Adjustable output to 150 Vac, with  $\pm$  0.02% accuracy at 100 Hz, and  $\pm$  0.1% accuracy from 10 KHz to 50 KHz.

**AC Current Source:** 

Adjustable output to 2 mA, with  $\pm 0.06\%$  accuracy at 1 KHz.

**Standard Resistance Elements:** 

Values known to within 20 ppm.

#### 4.3 Access to Calibrating Adjustments

Before attempting to recalibrate the Model 2590, the instrument should be allowed to warm up for at least 1/2 hour with the top cover in place so that all components come up to operating temperature. In addition, after the adjustments are completed, the cover should be replaced, the instrument allowed to warm up again, and the recalibration performance rechecked.

The calibrating adjustments for the Model 2590 are available when the top cover is removed. Observe the warning concerning high voltages. As shown in Figure 4-1, some of the adjustable components are located beneath the shield cover, and some are directly accessible on their assembly boards.

Do not remove the shield.

Follow the step-by-step procedures described in tabular form in the order of each of the succeeding subparagraphs.



Fig. 4-1. Access to Calibrating Adjustments

#### **4.4 PROCEDURES**

#### **DCV Adjustments:**

Connect the adjustable DC Voltage Standard to the input terminals.

Select DCV Measuring Mode.

Select the Full Scale Range shown in the table.

Set the input to the value shown in the table.

Adjust the specified calibration control until the displayed value equals the input setting.



\*Any value between  $+10V$  to  $+17V$  may be used.

#### **Resistance Measurement Calibration:**

Select KQ Measurement Mode, 4W setup.

Connect standard resistance values as shown in the INPUT column to the Model 2590, using the 4-wire connection mode. Other resistance values near full scale may be used instead of the values shown in the table.

Adjust the specified calibration control until the displayed value is exactly equal to the known input.



#### **MODEL 2590 SERIES DMM 62·5016**

**62·5016**

-

#### **ACV Calibration:**

Connect the output of the AC Voltage Standard to the Model 2590 input terminals.

Select the ACV Measuring Mode.

Select the range scale value shown in the table.

Set the AC Voltage Standard output to the rms value shown in the INPUT column of the table.

Adjust the specified calibrating control until the displayed value exactly equals the set input value.

#### **For Model 2590 (Average Sensing)**



#### **For Model 2590R (True RMS Sensing)**



#### **AC Current Calibration:**

Connect the AC Current Standard output to the Model 2590 input terminals.

Select the ACmA Measuring Mode.

Select the 2mA full scale range.

Set the current standard output to 1.50000mA at 1KHz.

Adjust A1R76 until the displayed value exactly equals the set input value.

**NOTES:**

.•.

## **Chapter 5 PRINCIPLES OF OPERATION**

#### **5.1 INSTRUMENT BLOCK DIAGRAM**

#### 5.1.1 **Generai**

As shown in Figure 5-1, the 2590 DMM consists of the following major functional blocks:

a. Front Panel Input switching functions to configure the circuitry for the selected measurement mode;

b. Input signal scaling and signal conditioning to develop a dc signal of 2-volts full scale for the selected fullscale range;

c. Analog-to-digital conversion of the scaled and condìtioned input, including the necessary timing logic for the conversion;

d. Display of the digitized signal, including polarity sign (for dc measurements) and decimai point for the selected full scale range;

e. Power supply to develop the appropriate analog and digital supply voltages.

This chapter describes the principles of operation of the circuitry incorporated in these blocks and this paragraph provides an overview of system operation. The remaining subparagraphs of this introduction briefly review the operation of the major blocks. Subsequent paragraphs describe the component operation, and are supported by simplified circuit schematics derived from complete schematics that are bound into the rear of this manual.



### **5\_1\_2 Measurement Modes and Input** Signa I **Conditioning**

Front-panel selection of a measurement mode connects the input signal to the appropriate signal scaling block. As indicated in the diagram: a separate scaling is performed for ac and dc voltages; a current shunt is used to convert both ac and dc current inputs to proportional voltages; ac voltages from the scaled input or from the shunt are then converted to dc voltages; and a separate current sourcing ciruit is used for resistance measurements.

The mode switching configures the input for 2-wire or 4-wire configurations for resistance measurement; current measuring circuits are fused for 2A limits. The ACIDC conversion may be accomplished by average-sensing and rms scaling (Model 2590), or may be performed for true rms conversions (ModeI 2590R).

#### **5\_1\_3 Analog-to-Digital Conversion**

The analog-to-digital conversion is accomplished by an integrating technique in three time segments, or phases:

a. Phase 1: a fixed time during which the analog input is disconnected from the converter, and the conversion circuit is automatically zeroed, while the standard 1-volt reference is "refreshed";

b. Phase 2: a fixed time during which the conditioned input is connected to the converter to cause the charge on the integrating capacitor to "ramp up" to a voltage proportional to the input magnitude and with a polarity depending upon the input polarity (for dc measurements);

c. Phase 3: a variable time during which the signal is disconnected from the input and a fixed reference voltage of opposite polarity to the signal during phase 2 is connected to the converter to cause the charge on the integrating capacitor to "ramp down" to its starting zero level. The time of phase 3 is read out as the digitized measurement.

**62-5016**

A timing control logic circuitry block (within the analoq-todigital block) is driven from a crystal-controlled master oscillator and develops the phase control timing signals from timing counters within the block and from sensed output of the Comparator. The Comparator senses the voltage at the output of the dual-ramp integrator.

At the end of phase 2, the comparator output is an indicator of the polarity of the integrator output, and hence, of the polarity of the input signal. This results in a setting of the polarity of the display and of the selection of positive or negative reference voltage for the phase 3 operation.

The timing control counts the duration of phase 3, and when the output of the comparator crosses zero, this signals the end of that phase (end of conversion). The logic circutry also places a limit on the duration of phase 3 at 199,999 counts. If the end of conversion signal is not sensed from the comparator by that time, the input is out-of-range, and the timing control causes two operations:

a. Sets up the out-of-range display signals;

b. Changes the time constant of the ramp-down circuit in the integrator to speed up the discharge of the capacitor and introduces an additional drive signal to speed up the discharge stili more. This is done to assure that the capacitor will be completely discharged during the auto zeroing action of phase 1.

The timing logic block also controls the gain of the amplifier ahead of the integrator. The block receives an indication of the full-scale range selection, and, for the lowest range (200mV), causes the amplifier to be configured with a gain 10 times greater than used for other ranges. This replaces the scaling function at the front end.

#### MODEL 2590 SERIES DMM 62-5016

#### 5\_1.4 System Timing

Figure 5-2 summarizes the timing relationships described above. The system timing is illustrated with respect to the signal at the output of the integrating capacitor of the dualramp analog-to-digital conversion. A number of different input signals are illustrated:

- a. An in-range positive input signal;
- b. An in-range negative input signal;
- c. An out-of-range positive input signal.

Note the change in slope of the ramp-down segment when the capacitor does not return to zero within the time limits of phase 3. Note, also, a 1-count delay between the end of phase 2 and the start of phase 3. This is introduced to assure that ali switching conditions will be completed before the ramp-down process is begun.



© ANALOGIC CORPORATION, DATA PRECISION DIVISION 5-5

#### 5.2 INPUT TERMINALS/MODE SWITCHING

Mode switches S2 through S6 are used to select the measurement mode at the front panel. They are interlocked so that selecting one of them releases a previous selection (except for S5 which controls the selection of 2-wire or 4-wire resistance measurement). Figure 5-3 is a simplified schematic of the switching controls and illustrates their actions on the signals connected to the banana jacks at the front-panel.

The HI input is connected to separate signal scaling circuits for dc volts, ac volts, or for current measurements. Until a resistance measurement is selected by S4, the LO input is conected to analog ground, and the resistance sensing from the HI input is disconnected, and the lead connected to analog ground.

When S4 is operated for a resistance mesurement, then the status of S5 (2W/4W) is significant. When a 2-wire measurement is to be made, the current sourcing is applied through the HI (J2) terminai, and the LO (J3) terminai is connected to analog ground. When a 4-wire measurement is to be made, the current sourcing is applied through HICS (J1), while LOCS (J4) is connected to analog ground.



#### MODEL 2590 SERIES DMM 62-5016

The operation of either S6 or S7 will connect the input to the current shunt. However, a distinction is required for later circuit application, to determine the introduction of the *ac/dc* converter assembly for ac currents.

5.3 SIGNAL CONDITIONING

#### 5.3.1 Generai

The function of the signal conditioning circuits is to develop a dc voltage proportional to a full scale of 2 volts for subsequent digitizing. As noted previously, the signal conditioning is performed in separate circuitry for each of the measuring modes. Details for each are contained in the subparagraphs that follow.

#### 5.3.2 DCV Signal Conditioning

Figure 5-4 is a simplified schematic of the signal conditioning circuitry that is configured when the front-panel switch DCV (S2) is pressed for this measurement mode. Switch positions for the 2V-range selection are indicated in their connected position (one, and only one range switch , may be be actuated at a time). The actuated contact resulting from the frontpanel range selection is identified in the illustration by the front-panel nomenclature. The output to the A/D converter circuitry is the voltage with respect to analog ground at the arm of S2 at the right end of the illustration.

As shown in Figure 5-4, the signal conditioning is essentially a resistance divider network to scale the input signa!. However, unlike the standard form of divider in which the divider remains fixed while taps provide different ratios, the divider is reconfigured for different ranges, and the same tap may be used for different ranges. Notice that there are only 2 taps at R65 and R63 across the main resistance string, and these 2 plus the connection at the top serve ali 5 voltage ranges. The reconfiguration is accomplished by the action of the circuit containing active element Z10.





For the 200V and 2000V ranges. for example, non-inverting input to Z10 is connected to analog ground, while the inverting input is connected to the bottom tap. The scaled output is taken from R63 for 2000V and from R65 for 200V. For 200mV, 2V, and 20V ranges, amplifier Z10 effectively shorts out the 9.9MQ resistor group (including R62 and the tapped R65). For the 200mV and 2V ranges, the output is connected directly (through three 33K resistors) to the input without further scaling. No switching is required for the 20V range (connections are as shown). A change in the amplifier gain at the input to the AID accomplishes the appropriate scaling for the 200mV.



### 5.3.3 **ACV Signal Conditioning**

The signal conditioning for ac voltage measurements is accomplished in two parts: scaling and *ac/dc* conversion. Figure 5-5 is a simplified schematic of the scaling operation, and Figures 5-6 and 5-7 are schematics of the *ac/dc* conversion for average sensing in Model 2590 (Figure 5-6), and true rms conversion in Model 2590R (Figure 5-7).

As shown in Figure 5-5, the scaling is accomplished by setting up the gain around amplifier Z1-7 by operating the appropriate front-panel range switch. Gain ratios from unity to *1/1000* are obtained.

For Model 2590, the average sensing and scaling to rms of an equivalent sinusoid is accomplished as shown in Figure 5-6. The scaled input from the previous circuit is ac-coupled to the ac/dc assembly and connected to the input of Z1 of that assembly through a precision 2.23K resistance and a series trimpot. The precision feedback resistance of 4.99K around the amplifier provides a gain factor of 2.2 in order to accomplish the scaling to the rms value of a sinusoid that has the equivalent average value being sensed. The dc output is connected via the mode switch to the AID circuitry.



 $\rightarrow \textcircled{2} \nrightarrow$ 

→©*ဗ္ဇ* 

۲J.

For the Model 2590R, the sensing and scaling to a true rms dc value is accomplished in a single integrated circuit, Z1 in that asembly, as shown in Figure 5-7. The signal is accoupled to the converter and connected to the input through a series trimpot.

#### 5.3.4 Current Measurements Signal Conditioning

Figure 5-8 is a simplified schematic of the signal conditioning for ac and dc current measurements. Both measurement modes use the tapped current shunt consisting of resistors R69 through R73 for the scaling; the divider action is obtained by operating the appropriate range selector switch. For the DCmA measurement mode, the shunt output is a dc voltage that may be connected directly as the *AID* circuit input.

For the ACmA measurement mode, the scaled ac output of the shunt is connected to the installed *ac/dc* converter circuit, as described above, for the Model 2590 (average sensing) or Model 2590R (true rms sensing) instruments.



### 5.3.5 Resistance Measurement Signal Conditioning

As noted in the earlier paragraphs of this chapter, the resistance measurement employs the technique of driving a constant current of known magnitude through the resistance to be measured and through a known resistance standard. Then, the DMM measures the ratio of the voltages across these resistances. The current source and sink and the voltage high and low sense may be connected in a 2- or 4-wire configuration. (Refer to the oprating instructions in Chapter 3.) Figure 5-9 is a simplified schematic of the signal conditioning circuit employed in the Model 2590. The illustration also includes some of the switching whereby the sensed voltage across the unknown resistance and the reference voltage appplied to the *AID* converter circuits during appropriate phases of the conversion cycle. These latter actions will be described in later paragraphs.

The constant drive current is developed in the amplifier Z6 circuit. The inverting input terminai of Z6 is connected to a value of 3.8 volts obtained from the divided down supply of 4.8 volts. The standard resistance,  $R_S$ , in series with the 4.8V supply, Q5, 1K, and the unknown resistance, is selected by operating the appropriate front-panel range switch. The current through this resistance is forced to drop the voltage to the non-inverting terminai of Z6 to 3.8V, or to produce a 1V drop across the range-selected precision resistance.

The same current that flows through the standard resistance also flows through the resistance to be measured,  $R_X$ . The drop across the unknown resistance is the input to the *AID* converter during phase 2.

During phase 3, the 1-volt drop across the standard resistance is connected through C2 to become the negative 1-volt reference for the *AID* input. Thus, the *AID,* in effect, is measuring the ratio of the voltages across the unknown and standard resistances. Because these voltages have been produced by a common current, their values are proportional to the resistances, and the resistance measurement is valid.



### 5.4 AlD CONVERSION

### 5.4.1 Analog Section

As indicated in the generai description at the start of this chapter, the conditioned input is connected during phase 2 to charge an integrating capacitor for a fixed time interval of 100 milliseconds; the reference is connected during phase 3 to reduce the charge on the capacitor. The operation, in effect, "ratios" the conditioned signal to the reference voltage.

Control signals from the digital section reconfigure the analog section for its performance during the separate phases of the conversion cycle. The time intervals of phases 1 and 2 are developed from the timing counter and logic gates, while the output of the analog comaparator circuit is sensed to determine the phase 3 time interval.

As shown in the complete schematic at the rear of the manual, the analog section consists of a dual FET pre-amplifier input stage 01, a programmable amplifier stage Z5, an integrator and amplifier stage Z3/Z2, and a comparator stage Z7. Figure 5·10 is a simplified schematic of the portion of the circuit beginning with the input to Z3.



©ANALOGIC CORPORATION. DATA PRECISION DIVISION 5·15

5·14

During phase 1, the analog circuit is autozeroed. The input to the analog circuitry is grounded, and the output of the comparator is connected to the input of the integrator stage and to offset capacitor C17 by the switch control of  $\Phi$ 1 (in the Switch Module). Then, for the 100ms duration of phase 1, a charge will accumulate across C17 so as to compensate for ali the non-zero offsets and drifts in the circuitry and to drive the comparator output to zero. The charge stored on C17 remains in the circuit for both the remaining phases. Note that its value is updated once each conversion cycle.

During phase 2, the conditioned signal input is connected to one side of the Q1 dual FET through a switch closed by the  $\Phi$ 2 signal. The other side of the dual FET receives the feedback signal from the programmable gain amplifier output through either switch A or switch B. These latter switches are selected to introduce a gain factor of 10 for the 200mV range scale. The output of the programmable gain amplifier is integrated in the Z3 stage for a fixed time interval of 100ms, and the output voltage at that time is proportional to the conditioned input signa!.

Compound amplifier Z2/Z7 form a high-gain comparator that is driven into saturation with the opposite polarity of the integrator output. This polarity is sensed in the logic circuitry where its sense determines the selection of the proper polarity of reference signal to be connected to the input during phase 3.

### 5.4\_2 AlD Reference Generation (Isopolar)

Generation of the reference voltage for voltage and current measurement modes is illustrated in the simplified schematic of Figure 5-11. The precision reference of 6.6 *volts* is divided down in the resistance network so that a *1-volt* magnitude is connected to one arm of switch S4. (The switch is positioned for the nonresistance measurement modes.) During phase 1, the *1-volt* level charges capacitor C2 through R1 and R88. The charge across the capacitor remains when the phase 1 switches are open, and is disconnected from the input to the A/D by the action of the  $\overline{\Phi2}$ control signal.

#### MODEL 2590 SERIES DMM 62-5016 62-5016 62-5016 62-5016 MODEL 2590 SERIES DMM 62-5016

If the input had been a positive signal, then  $\phi$ 3(+) control signal is received from the timing control logic and connects the top of C2 to analog ground (through terminai E3 and the S4 switch contact). This action shifts the level of the lower side of C2 to 1 volt below ground level, and connects it to the A/D input. If the input signal had been a negative signal, then  $\Phi(3(-))$  control signal causes the positive 1-volt reference to be connected to the A/D circuit.

For resistance measurement modes, refer to Figure 5-8, in which the signal conditioning had been described. During phase 1, the 4.8V reference supply is connected through the closed phase 1 switches to charge C2 through R1 and R88. During phase 3, the voltage level at the non-inverting input to Z6 (which is less than 4.8V by the drop across the standard resistance) is connected to the top of C2. The lower side of C2 is then driven below ground by the value of the voltage drop across the standard range resistance, and that negative reference is used during phase 3 to drive the A/D converter circuitry, as required.



62·5016

#### 5.4.3 Timing Control Logic

The timing control logic circuitry is illustrated in the simplified block schematic of Figure 5-11. The function of these blocks is to generate the control signals for ali the switches identified in the previous circuits, and to generate the control siqnals for the 5%-digit display.

As shown in the illustration, the circuit incorporates a 4-MHz crystal controlled oscillator, from which the basic timing clock pulses of 1 MHz are derived. The 1MHZ clock drives a counter chain consisting of an initial decade counter, IC Z14, followed by four stages of divide-by-10 in another IC, Z10, followed by a 4-decade counter IC Z11; or a total of 9 decades. The output of Z10 is a pulse train of 100-millisecond period, and is the basic count for the three phases. The first carry output from Z10 causes a switch from the phase 1 to phase 2; the second carry is sensed as the first count from Z11 and causes a switch from phase 2 to phase 3, but only after a "pulse hog" circuit removes one pulse from the clock train. This delay provides time for all the switched circuitry to stabilize before starting phase 3. The COMP signal at the



#### **MODEL** 2590 **SERIES DMM** 62·5016

end of Phase 1 sets a flip flop to gate the appropriate reference polarity control from the circuit when the phase 3 portion of the cycle is to start.

When the COMP signal changes at the end of conversion of an in-range signal, it is clocked by the next clock pulse to latch the values in Z14, Z10, and Z7. Z14 transmits the parallel BCD value of the LSD; Z10 cutputs a series of paratlel addressed 4-bit BCD codes for the next four digits; Z7 outputs the controls for the MSD. The counters are reset for the start of the next conversion cycle.

When an out-of-range signal permits the third decade carry before the COMP signal indicates end of conversion, Z11 is configured to produce a carry pulse from the O digit which sets the FC control signal circuitry and blanks the MSD.

NOTES:

**r**

# Chapter 6 **MAINTENANCE**

#### CAUTION

Your Multimeter is covered by a 12-month warranty and should be referred to the factory or Authorized Service Centers for maintenance within the warranty period. Attempts to make any extensive repairs within the warranty period may invalidate this warranty. If repairs are needed after the warranty period, only qualified technicians should attempt to effect such repairs and should use test instruments and standards calibrated with the accuracies and tolerances of the performance specifications of the instrument.

#### WARNING

High voltages are accessible within the instrument when the cover is removed. Proceed with caution when making any measurements within the instrument. Disconnect power and discharge powersupply filter capacitors before making repairs.

#### 6.1 TROUBLE·SHOOTING STRATEGY

The Model 2590 OMM is particularly responsive to a welldefined strategy of trouble-shooting analysis because of its modular funtion architecture. That is, the OMM performance in a particular measurement mode utilizes a unique portion of the instrument circuitry, and proper performance in that mode demonstrates the proper operation of ali the circuit groups lnvolved. Where some modular circuit function blocks are operative in several measurement modes, it may be possible to isolate the trouble to a particular block (or even to a circuit component) by thoughtful analysis of the results in several measurement modes.

The flow chart of Figure 6-1 defines a trouble-shooting strategy based on the "positive" approach of defining proper-Iy operating circuit blocks, and thereby isolating the cause of trouble to a block or circuit component.



.,



**d**

In many instances, a logical analysis of the instrument response to varying setups will isolate the probable source of trouble without opening the case.

You will note, in Figure 6-1, that the initial reaction to a detected malfunction is to verify the input connections. In other words, start with an assumption of "cockpit error" rather than instrument error. An apparent malfunction is often the result of disturbed input connections or a failure in the source of the signal to be measured.

When the analysis leads to an indicated repair/replacement action, as shown in the illustration, a functional block is identified within a coded graphic symbol. That function has been described in some detail in Chapter 5, and the compiete schematic is included at the back of the book.

#### 6.3 POWER SUPPLY

When no display is observed, and the DMM appears to be completely non-functioning, the fault may be in the power or in the display assembly (see Fig. 6-1.). The power supply circuit is instrumented with convenient test points, at which the various supply levels used in the instrument may be measured. Refer to Table 6-1 and to Figure 6-2 for further details.

#### 6.4 AlO CONVERTER

As described in Chapter 5, the A/D conversion is performed in a circuit comprising separate components (as distinct from an integrated circuit assembly). When the analysis suggests a malfunction in that functional circuit, the further troubleshooting is aided by test points located along the conversion flow path. These were identified on the simplified schematic in Chapter 5; they are also shown on the complete schematic in the rear of the book; and further defined in Table 6-1. Their locations are shown in Figure 6-2. Refer to Figure 6-3 for a description of the typical waveforms to be measured at these points.









 $\begin{array}{c}\n1 \quad \text{PHASE 1} \\
100 \text{MSE}\n\end{array}$ 

 $\iota$ 

 $\bar{k}$  .)

PHASE 3<br>200MSEC

PHASE 3

© ANALOGIC CORPORATION, DATA PRECISION DIVISION

 $6 - 7$ 

 $\mathcal{L}_{\mathcal{A}}$ 

## Chapter 7 PARTS LlSTS

#### 7.1 MODEL 2590 DMM ASSEMBLIES

Figure 7·1 illustrates the breakdown of the Multimeter into its major assemblies within the case. Four major assemblies (A1, A2, A3, and A4) are common to the two configurations, 2590 and 2590R. The fifth board assembly determines the performance and designation of the instrument as a 2590 (Schematic 65·1038) for Average Sensing, and as a 2590R (Schematic 65·1037) for True RMS Sensing. Transformer and wiring modifications in the case rear panel assembly determine the power sourcing configuration for the instrument.

#### 7.2 PARTS LlSTS

#### 7.2.1 Generai

The parts lists that follow cover the replaceable electronic components for the separate assemblies. The Iists are presented in the grouping according to the assemblies to which they refer. Parts locations are shown on the corresponding assembly drawings that are included with this manual.

#### 7.2.2 Ordering Requirements

When replacement parts are required, the order should specify:

The part Reference Designation (for example: R1, C200, etc) as shown on the schematic or assembly board;

The complete Part Description as in the tabular listing; The Data Precision Part Number (for example: DP Part No. 22·021029, etc.) as shown in the Iistings that follow.; and

The Part Number and Revision Letter of the pc-board on which the part is located.





©ANALOGIC CORPORATION, DATA PRECISION DIVISION

# **MODEL** 2590 SERIES DMM 62-5016<br>
MAIN PCB ASSEMBLY (PL60-1117) (continued) 62-5016<br>
MAIN PCB ASSEMBLY (PL60-1117) (Continued)



#### **MAIN PCB ASSEMBLY** (PL60-1117) (continued) **MAIN PCB ASSEMBL Y** (PL60-1117) (Continued)





## MAIN PCB ASSEMBLY (PL60-1117) (Continued)



# MODEL 2590 SERIES DMM 62-5016<br>
MODEL 2590 SERIES DMM 62-5016<br>
MODEL 2590 SERIES DMM 62-5016<br>
7.4 LOGIC PCB ASSEMBLY (67-115)



• Ali resistance values in ohms, except where otherwise specified.

T-6 © ANALOGIC CORPORATION, DATA PRECISION DIVISION © ANALOGIC CORPORATION, DATA PRECISION DIVISION 7-7

# **MODEL** 2590 SERIES DMM 62-5016<br>
7.5 DISPLAY PCB ASSEMBLY (67-1116) 62-5016



## **7.6 FRONT BEZEL ASSEMBLY (67·1119)**



### **7.7 REAR PANEL ASSEMBL Y (67·1120)**



## **7.8 AVERAGE ACIDC ASSEMBLY (67·1113)**



#### **7.9 RMS AC/DC ASSEMBLY (67·1114)**



Resistor values in ohms, unless otherwise defined. Resistance in ohms, unless otherwise defined.

**NOTES:**

 $\epsilon$ 

# **Chapter 8**

# **REFERENCE DRAWINGS**

Assembly Drawings: Main PCB (A1): 67-1117 Display PCB (A2): 67-1116 Logic PCB (A3): 67-1115 Switch Module (A4): 67-1130 Front Bezel: 67-1119 Rear Panel: 67-1120 ACG ACIDC PCB (A5): 67-1113 RMS *AC/DC* PCB (A5): 67-1114

Schematics:

Main PCB (A1): 65-1040 Sheet 1) Logic (A3) and Disptay (A2): 65-1040 (Sheet 2) Switch Module (A4): 65-1039 AVG ACIDC (A5): 65-1038 RMS ACIDC (A5): 65-1037



![](_page_37_Figure_0.jpeg)

![](_page_38_Figure_0.jpeg)

![](_page_39_Figure_0.jpeg)

![](_page_39_Figure_1.jpeg)

![](_page_40_Figure_0.jpeg)

![](_page_41_Picture_19.jpeg)

![](_page_41_Figure_1.jpeg)

![](_page_42_Figure_0.jpeg)

![](_page_43_Figure_0.jpeg)

![](_page_44_Figure_0.jpeg)

![](_page_44_Figure_1.jpeg)

![](_page_45_Figure_0.jpeg)

THESE DRAWINGS AND SPECIFICATIONS ARE<br>THE PROPERTY OF DATA PRECISION CORPORATIONS CONTINUES<br>COPIED OR USED AS THE BASES FOR MANU-<br>FACTURE OR SALE OF APPARATUS WITHOUT<br>FACTURE OR SALE OF APPARATUS WITHOUT

 $\overline{\mathbb{I}}$ 

![](_page_46_Figure_0.jpeg)